#### Linear-Time Logic

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**2** Linear Time Logic: Equivalences (Section 5.1.4)

**3** Linear Time Logic: Additional Operators (Section 5.1.5)

Linear Time Logic: Specifying Fairness (Section 5.1.6)



- An LT property is a set of infinite traces over AP.
- Specifying such sets explicitly is often inconvenient.
- Mutual exclusion is specified over  $AP = \{ c_1, c_2 \}$  by

 $P_{mutex} \ = \ {
m set} \ {
m of} \ {
m infinite} \ {
m words} \ A_0 \ A_1 \ A_2 \dots \ {
m with} \ \{ \ c_1, c_2 \ \} 
ot \subseteq A_i \ {
m for} \ {
m all} \ i \ge 0$ 

- Starvation freedom is specified over  $\textit{AP} = \{\,c_1, w_1, c_2, w_2\,\}$  by

 $P_{nostarve} =$  set of infinite words  $A_0 A_1 A_2 \dots$  such that:

 $\left(\stackrel{\infty}{\exists} j. w_1 \in A_j\right) \Rightarrow \left(\stackrel{\infty}{\exists} j. c_1 \in A_j\right) \land \left(\stackrel{\infty}{\exists} j. w_2 \in A_j\right) \Rightarrow \left(\stackrel{\infty}{\exists} j. c_2 \in A_j\right)$ 

#### Such properties can be specified succinctly using linear temporal logic.

#### **1** Linear Time Logic: Syntax & Semantics (Section 5.1.1 - 5.1.3)

- **2** Linear Time Logic: Equivalences (Section 5.1.4)
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- 5 Automata-Based LTL Model Checking

# 5.1.1 Linear Temporal Logic (LTL): Syntax

- Linear temporal logic is a logic for describing LT properties.
  - An extension of propositional logic with temporal modalities.
- Modal logic over infinite sequences [Pnueli 1977].
- Propositional logic:
  - $a \in AP$
  - $\neg\phi$  and  $\phi~\wedge~\psi$
- Temporal operators:
  - $\bigcirc \phi$  neXt state fulfills  $\phi$ •  $\phi \cup \psi$   $\phi$  holds Until a  $\psi$ -state is reached
- Syntax of LTL over  ${\cal AP}$

 $\varphi \ ::= \ true \ | \ a \ | \ \varphi \land \varphi \ | \ \neg \varphi \ | \ \bigcirc \ \varphi \ | \ \varphi \ \mathsf{U} \ \varphi$ 

where  $a \in AP$  is an atomic proposition.

atomic proposition negation and conjunction

#### LTL Derived Operators

#### Precedence order:

- The unary operators bind stronger than the binary ones.
- $\neg$  and  $\bigcirc$  bind equally strong.
- U takes precedence over  $\wedge,\,\vee,$  and  $~\rightarrow~.$













## New Temporal Modalities $\Diamond$ and $\Box$

## New Temporal Modalities $\Diamond$ and $\Box$

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- Once red, the light cannot become green immediately
- The light becomes green eventually:  $\Diamond$  green
- The light becomes green infinitely often:  $\Box \Diamond green$
- Once red, the light becomes green eventually:  $\Box$  (red  $\rightarrow$   $\Diamond$  green)
- Once red, the light always becomes green eventually after being yellow for some time in-between:

 $\Box(\mathit{red} \to \bigcirc (\mathit{red} \: \mathsf{U} \, (\mathit{yellow} \land \bigcirc (\mathit{yellow} \: \mathsf{U} \, \mathit{green}))))$ 

 $\Box$  (red  $\rightarrow \neg \bigcirc$  green)

Note these properties assume European traffic light which goes red, red/yellow, green, yellow, repeat.

# LTL General Semantics (5.1.2)

Let 
$$\sigma = A_0 A_1 A_2 \ldots \in (2^{AP})^{\omega}$$
.

 $\sigma \models \text{true}$ 

- $\sigma \models a \qquad \text{iff} \quad a \in A_0 \quad (\text{i.e., } A_0 \models a)$
- $\sigma \hspace{0.2cm} \models \hspace{0.2cm} \varphi_1 \hspace{0.2cm} \land \hspace{0.2cm} \varphi_2 \hspace{0.2cm} \text{iff} \hspace{0.2cm} \sigma \models \varphi_1 \hspace{0.2cm} \text{and} \hspace{0.2cm} \sigma \models \varphi_2$
- $\sigma \hspace{0.2cm} \models \hspace{0.2cm} \neg \hspace{0.2cm} \varphi \hspace{0.2cm} \text{iff} \hspace{0.2cm} \sigma \not\models \varphi$
- $\sigma \models \bigcirc \varphi$  iff  $\sigma[1..] = A_1 A_2 A_3 \ldots \models \varphi$
- $\sigma \hspace{0.2cm} \models \hspace{0.2cm} \varphi_1 \, {\sf U} \, \varphi_2 \hspace{0.2cm} \text{iff} \hspace{0.2cm} \exists j \geq 0. \hspace{0.2cm} \sigma[j..] \models \varphi_2 \hspace{0.2cm} \text{and} \hspace{0.2cm} \sigma[i..] \models \varphi_1, \hspace{0.2cm} 0 \leq i < j$

where  $\sigma[i..] = A_i A_{i+1} A_{i+2}...$  is suffix of  $\sigma$  from index i on.

#### General Semantics of $\Box$ , $\Diamond$ , $\Box \Diamond$ and $\Diamond \Box$

Let  $\sigma = A_0 A_1 A_2 \dots \in (2^{AP})^{\omega}$ .  $\sigma \models \Diamond \varphi \quad \text{iff} \quad \exists j \ge 0. \ \sigma[j..] \models \varphi$   $\sigma \models \Box \varphi \quad \text{iff} \quad \forall j \ge 0. \ \sigma[j..] \models \varphi$   $\sigma \models \Box \Diamond \varphi \quad \text{iff} \quad \forall j \ge 0. \ \exists i \ge j. \ \sigma[i \dots] \models \varphi$  $\sigma \models \Diamond \Box \varphi \quad \text{iff} \quad \exists j \ge 0. \forall i \ge j. \ \sigma[i \dots] \models \varphi$ 

where  $\sigma[i..] = A_i A_{i+1} A_{i+2}...$  is suffix of  $\sigma$  from index i on.

The LT-property induced by LTL formula 
$$\varphi$$
 over  $AP$  is:  
 $Words(\varphi) = \left\{ \sigma \in \left(2^{AP}\right)^{\omega} \mid \sigma \models \varphi \right\}$ , where  $\models$  is the smallest satisfaction relation.

Let  $TS = (S, Act, \rightarrow, I, AP, L)$  be a transition system without terminal states, and let  $\varphi$  be an LTL-formula over AP.

• For infinite path fragment  $\pi$  of *TS*:

$$\pi \models \varphi$$
 iff  $trace(\pi) \models \varphi$ 

• For state  $s \in S$ :

 $s \models \varphi$  iff  $\forall \pi \in Paths(s). \ \pi \models \varphi$ 

• **TS** satisfies  $\varphi$ , denoted **TS**  $\models \varphi$ , iff **Traces**(**TS**)  $\subseteq$  **Words**( $\varphi$ )

 $\mathit{TS} \models \varphi$ 

- iff (\* transition system semantics \*)  $Traces(TS) \subseteq Words(\varphi)$
- iff (\* definition of  $\models$  for LT-properties \*)  $TS \models Words(\varphi)$

iff (\* Definition of 
$$Words(\varphi)$$
 \*)  
 $\pi \models \varphi$  for all  $\pi \in Paths(TS)$ 

$$\begin{array}{ll} \text{iff} & (\texttt{* semantics of}\models\texttt{for states}\;\texttt{*})\\ s_0\models\varphi\;\texttt{for all}\;s_0\in I & . \end{array}$$







 $TS \models \Box a$  $TS \models \bigcirc (a \land b)?$ 



$$TS \models \Box a$$
$$TS \not\models \bigcirc (a \land b)$$
$$TS \models \Box (\neg b \rightarrow \Box (a \land \neg b))?$$



$$TS \models \Box a$$
$$TS \not\models \bigcirc (a \land b)$$
$$TS \models \Box (\neg b \rightarrow \Box (a \land \neg b))$$



$$TS \models \Box a$$
$$TS \not\models \bigcirc (a \land b)$$
$$TS \models \Box (\neg b \rightarrow \Box (a \land \neg b))$$
$$TS \models b \cup (a \land \neg b)?$$



$$TS \models \Box a$$
  

$$TS \not\models \bigcirc (a \land b)$$
  

$$TS \models \Box (\neg b \rightarrow \Box (a \land \neg b))$$
  

$$TS \not\models b \cup (a \land \neg b)$$

• For paths, it holds  $\pi \models \varphi$  if and only if  $\pi \not\models \neg \varphi$  since:

$$Words(\neg \varphi) = (2^{AP})^{\omega} \setminus Words(\varphi)$$

- But:  $TS \not\models \varphi$  and  $TS \models \neg \varphi$  are *not* equivalent in general.
- It holds:  $TS \models \neg \varphi$  implies  $TS \not\models \varphi$ , not always the reverse!
- Note that:

$$\begin{array}{ll} TS \not\models \varphi & \text{iff } Traces(TS) \not\subseteq Words(\varphi) \\ & \text{iff } Traces(TS) \setminus Words(\varphi) \neq \emptyset \\ & \text{iff } Traces(TS) \cap Words(\neg \varphi) \neq \emptyset \end{array}$$

*TS* neither satisfies φ nor ¬φ if there are paths π<sub>1</sub> and π<sub>2</sub> in *TS* such that π<sub>1</sub> ⊨ φ and π<sub>2</sub> ⊨ ¬φ.

# **Negation Example**



#### A transition system for which $TS \not\models \Diamond a$ and $TS \not\models \neg \Diamond a$ .

• N processes, each of which has an unique identity. Leader process is the one that has the largest ID.

#### **Example 5.13 Leader Election**

- N processes, each of which has an unique identity. Leader process is the one that has the largest ID.
- There is always one leader

$$\Box(\bigvee_{1 \leq i \leq N} leader_i \land \bigvee_{1 \leq j \leq N, j \neq i} \neg leader_j)$$
$$\Box \Diamond(\bigvee_{1 \leq i \leq N} leader_i \land \bigvee_{1 \leq j \leq N, j \neq i} \neg leader_j)$$
$$\Box \Diamond(\bigvee_{1 \leq i \leq N} leader_i)$$
$$\Diamond \Box(\bigvee_{1 \leq i \leq N} leader_i)$$

- N processes, each of which has an unique identity. Leader process is the one that has the largest ID.
- There must always be at most one leader

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$$\Box \bigwedge_{1 \le i \le N} (leader_i \to \bigwedge_{1 \le j \le N, j \ne i} \neg leader_j)$$

- N processes, each of which has an unique identity. Leader process is the one that has the largest ID.
- There must always be at most one leader

$$\Box \bigwedge_{1 \le i \le N} (leader_i \to \bigwedge_{1 \le j \le N, j \ne i} \neg leader_j)$$

• A correct leader will be elected eventually.

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5 Automata-Based LTL Model Checking

LTL formulas  $\phi, \psi$  are *equivalent*, denoted  $\phi \equiv \psi$ , if:  $Words(\phi) = Words(\psi)$ 

• Recall that The time complexity for invariant checking is:

$$\mathcal{O}(N*(1+|\Phi|)+M)$$

where

- N is the number of reachable states,
- M is the number of transitions in the reachable fragment of TS, and
- $|\Phi|$  is the length of  $\Phi$  number of logic connectives in  $\Phi$

#### **Duality and Idempotence Laws**



Idempotency:	$\Box \Box \phi$	$\equiv$	$\Box \phi$
	$\diamondsuit \diamondsuit \phi$	≡	$\Diamond \phi$
	$\phiU(\phiU\psi)$	≡	$\phiU\psi$
	$(\phi  U  \psi)  U  \psi$	≡	$\phiU\psi$

#### **Absorption and Distributive Laws**

Absorption:
$$\Diamond \Box \Diamond \phi \equiv \Box \Diamond \phi$$
 $\Box \Diamond \Box \phi \equiv \Diamond \Box \phi$ 

Distribution:  $\bigcirc (\phi \cup \psi) \equiv (\bigcirc \phi) \cup (\bigcirc \psi)$  $\Diamond (\phi \lor \psi) \equiv \Diamond \phi \lor \Diamond \psi$  $\Box (\phi \land \psi) \equiv \Box \phi \land \Box \psi$ 

but .....:  $\Diamond(\phi \cup \psi) \not\equiv (\Diamond \phi) \cup (\Diamond \psi)$  $\Diamond(\phi \land \psi) \not\equiv \Diamond \phi \land \Diamond \psi$  $\Box(\phi \lor \psi) \not\equiv \Box \phi \lor \Box \psi$ 

#### **Distributive Laws**



 $TS \not\models \Diamond (a \land b) \text{ and } TS \models (\Diamond a \land \Diamond b)$ 

Define U,  $\Diamond$ , and  $\Box$  by recursion.

Expansion:  $\Box \phi \equiv \phi \land \bigcirc \Box \phi$  $\Diamond \phi \equiv \phi \lor \bigcirc \Diamond \phi$  $\phi \cup \psi \equiv \psi \lor (\phi \land \bigcirc (\phi \cup \psi))$  Linear Time Logic: Syntax & Semantics (Section 5.1.1 - 5.1.3)

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• The *weak-until* (or: unless) operator:

$$\varphi \, \mathsf{W} \, \psi \quad \stackrel{\mathsf{\tiny def}}{=} \quad (\varphi \, \mathsf{U} \, \psi) \ \lor \ \Box \varphi$$

- $\varphi\,\mathrm{W}\,\psi$  does not require a  $\psi\text{-state}$  to be reached.
- Until U and weak until W are *dual*:

$$\begin{array}{lll} \neg(\varphi \, \mathsf{U} \, \psi) & \equiv & (\varphi \ \land \ \neg \psi) \, \mathsf{W} \left(\neg \varphi \ \land \ \neg \psi\right) \\ \neg(\varphi \, \mathsf{W} \, \psi) & \equiv & (\varphi \ \land \ \neg \psi) \, \mathsf{U} \left(\neg \varphi \ \land \ \neg \psi\right) \end{array}$$

• Until and weak until are equally expressive:

$$\Box \psi \equiv \psi \operatorname{W} \mathsf{false}$$
  
$$\varphi \operatorname{U} \psi \equiv (\varphi \operatorname{W} \psi) \land \neg \Box \neg \psi$$

• The *release* operator:

$$\begin{array}{rcl} \varphi \, \mathsf{R} \, \psi & \stackrel{\text{def}}{=} & \neg (\neg \varphi \, \mathsf{U} \, \neg \psi) \\ & \stackrel{\text{def}}{=} & (\neg \varphi \ \land \ \psi) \, \mathsf{W} \, (\phi \ \land \ \psi) \end{array}$$

•  $\psi$  always holds, a requirement that is released as soon as  $\varphi$  holds.



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5 Automata-Based LTL Model Checking

For set A of actions and infinite run  $\rho$ :

• Unconditional fairness

Some action in A occurs infinitely often along  $\rho$ .

• Strong fairness

If actions in A are *infinitely often* enabled (not necessarily always!) then some action in A has to occur infinitely often in  $\rho$ .

• Weak fairness

If actions in A are *continuously enabled* (no temporary disabling!) then it has to occur infinitely often in  $\rho$ .

This chapter uses *state-based* fairness assumptions (and constraints).

## 5.1.6 LTL Fairness Constraints

Let  $\Phi$  and  $\Psi$  be propositional logic formulas over AP.

**1** An *unconditional LTL fairness constraint* is of the form:

ufair =  $\Box \Diamond \Psi$ 

**2** A strong LTL fairness condition is of the form:

$$sfair = \Box \Diamond \Phi \longrightarrow \Box \Diamond \Psi$$

**3** A *weak LTL fairness constraint* is of the form:

$$\textit{wfair} ~=~ \Diamond \Box \Phi ~\longrightarrow ~ \Box \Diamond \Psi$$

 $\Phi$  stands for "something is enabled";  $\Psi$  for "something is taken"

For state s in transition system TS (over AP) without terminal states, let

$$\begin{array}{lll} \mathsf{FairPaths}_{fair}(s) & = & \left\{ \pi \in \mathsf{Paths}(s) \mid \pi \models fair \right\} \\ \mathsf{FairTraces}_{fair}(s) & = & \left\{ \operatorname{trace}(\pi) \mid \pi \in \mathsf{FairPaths}_{fair}(s) \right\} \end{array}$$

For LTL-formula  $\varphi$ , and LTL fairness assumption *fair*:

$$s \models_{fair} \varphi$$
 if and only if  $\forall \pi \in FairPaths_{fair}(s)$ .  $\pi \models \varphi$  and  
 $TS \models_{fair} \varphi$  if and only if  $\forall s_0 \in I$ .  $s_0 \models_{fair} \varphi$ 

 $\models_{fair}$  is the fair satisfaction relation for LTL;  $\models$  the standard one for LTL

#### Example 5.27 Randomized Arbiter



 $TS_1 \parallel Arbiter \parallel TS_2 \not\models \Box \Diamond crit_1$ But:  $TS_1 \parallel Arbiter \parallel TS_2 \models_{fair} \Box \Diamond crit_1 \land \Box \Diamond crit_2$ with  $fair = \Box \Diamond head \land \Box \Diamond tail$ 

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#### **Semaphore-Based Mutual Exclusion**



$$sfair_1 = \Box \Diamond wait_1 \rightarrow \Box \Diamond crit_1$$

#### **Semaphore-Based Mutual Exclusion**



$$fair = sfair_1 \land sfair_2$$

#### **Semaphore-Based Mutual Exclusion**



$$fair = sfair_1 \land sfair_2$$
$$TS_{Sem} \models_{fair} \Box \Diamond crit_1 \land \Box \Diamond crit_2$$

Comp Sys Verification

#### Theorem 5.30 Reducing $\models_{fair}$ to $\models$

For:

- A transition system TS without terminal states
- LTL formula  $\varphi$ , and
- LTL fairness assumption fair

It holds:

$$TS \models_{fair} \varphi$$
 if and only if  $TS \models (fair \rightarrow \varphi)$ 

# Verifying an LTL-formula under a fairness assumption can be done using standard verification algorithms for LTL.

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#### 5 Automata-Based LTL Model Checking

The following decision problem:

Given finite transition system *TS* and LTL-formula  $\varphi$ : yields "yes" if  $TS \models \varphi$ , and "no" (plus a counterexample) if  $TS \not\models \varphi$ 

See section 5.2 for details.

$$TS \models \varphi$$
 if and only if  $Traces(TS) \subseteq \underbrace{Words(\varphi)}_{\mathcal{L}_{\omega}(\mathcal{A}_{\varphi})}$ 

 $\text{ if and only if } \quad \textit{Traces}(\textit{TS}) \, \cap \, \mathcal{L}_{\omega}(\overline{\mathcal{A}_{\varphi}}) \; = \; \emptyset$ 

But complementation of NBA is quadratically exponential. If  $\mathcal{A}$  has n states,  $\overline{\mathcal{A}}$  has  $c^{n^2}$  states in worst case! Use the fact that  $\mathcal{L}_{\omega}(\overline{\mathcal{A}_{\varphi}}) = \mathcal{L}_{\omega}(\mathcal{A}_{\neg\varphi})!$   $TS \models \varphi$  if and only if  $Traces(TS) \subseteq Words(\varphi)$ 

if and only if  $Traces(TS) \cap ((2^{AP})^{\omega} \setminus Words(\varphi)) = \emptyset$ 

$$\text{if and only if} \quad Traces(TS) \cap \underbrace{Words(\neg \varphi)}_{\mathcal{L}_{\omega}(\mathcal{A}_{\neg \varphi})} = \emptyset$$

 $\begin{array}{ll} \text{if and only if} & TS \otimes \mathcal{A}_{\neg \varphi} \models \Diamond \Box \neg F \text{ where } F \\ \text{is the set of accepting states of } \mathcal{A}_{\neg \varphi}. \end{array}$ 

LTL model checking is thus reduced to persistence checking!

#### Some Examples: LTL to BGA



 $\Box \Diamond green$ 



$$\Box(a \to \Diamond b)$$



# **Overview of LTL Model Checking**



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