

# Computation Tree Logic

Hao Zheng

Department of Computer Science and Engineering  
University of South Florida  
Tampa, FL 33620  
Email: zheng@cse.usf.edu  
Phone: (813)974-4757  
Fax: (813)974-5456

- 1 Introduction (Section 6.1)
- 2 Computation Tree Logic (Section 6.2)
  - CTL - Syntax
  - CTL - Semantics
  - CTL Semantics - Equivalences
- 3 CTL Model Checking (Section 6.4)
- 4 Comparing CTL and LTL (Section 6.3)

- 1 Introduction (Section 6.1)
- 2 Computation Tree Logic (Section 6.2)
  - CTL - Syntax
  - CTL - Semantics
  - CTL Semantics - Equivalences
- 3 CTL Model Checking (Section 6.4)
- 4 Comparing CTL and LTL (Section 6.3)

# Introduction (6.1)

- *Linear* temporal logic:

“Statements about *(all) paths* starting in a state.”

- $s \models \Box(x \leq 20)$  iff for all possible paths starting in  $s$  always  $x \leq 20$ .
- Quantifier  $\forall$  is implicit:  $s \models \Box(x \leq 20) \equiv s \models \forall \Box(x \leq 20)$

# Introduction (6.1)

- **Linear** temporal logic:

*“Statements about (all) paths starting in a state.”*

- $s \models \Box(x \leq 20)$  iff for all possible paths starting in  $s$  always  $x \leq 20$ .
- Quantifier  $\forall$  is implicit:  $s \models \Box(x \leq 20) \equiv s \models \forall \Box(x \leq 20)$

- **Branching** temporal logic:

*“Statements about all or some paths starting in a state.”*

- $s \models \forall \Box(x \leq 20)$  iff for **all** paths starting in  $s$  always  $x \leq 20$ .
- $s \models \exists \Box(x \leq 20)$  iff for **some** path starting in  $s$  always  $x \leq 20$ .
- Nesting of path quantifiers is allowed.

# Introduction (6.1)

- **Linear** temporal logic:

“Statements about **(all) paths** starting in a state.”

- $s \models \Box(x \leq 20)$  iff for all possible paths starting in  $s$  always  $x \leq 20$ .
- Quantifier  $\forall$  is implicit:  $s \models \Box(x \leq 20) \equiv s \models \forall \Box(x \leq 20)$

- **Branching** temporal logic:

“Statements about **all or some paths** starting in a state.”

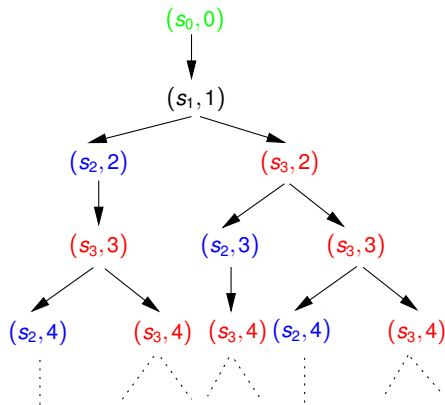
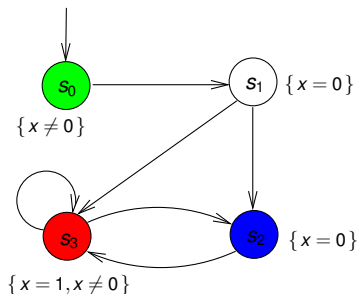
- $s \models \forall \Box(x \leq 20)$  iff for **all** paths starting in  $s$  always  $x \leq 20$ .
  - $s \models \exists \Box(x \leq 20)$  iff for **some** path starting in  $s$  always  $x \leq 20$ .
  - Nesting of path quantifiers is allowed.
- Checking  $\exists \varphi$  in LTL can be done using  $\forall \neg \varphi$ , but this does not work for nested formulas such as  $\forall \Box \exists \Diamond a$ .

In any state of every computation ( $\forall \Box$ ), it is possible ( $\exists \Diamond$ ) to return to the initial state.

$\Box \Diamond a$  vs  $\forall \Box \exists \Diamond a$ , difference?

# Computational Tree View of Transition Systems

- Semantics is based on a branching notion of time.
  - An infinite tree of states obtained by unfolding the transition system.
  - One “time instant” may have several possible successor “time instants”.



# Branching vs Linear Temporal Logics

- Incomparable expressiveness:
  - There are properties that can be expressed in LTL, but not in CTL.
  - There are also properties that can be expressed in CTL, but not in LTL.
- Distinct model-checking algorithms with different time/space complexities.
- Fairness assumptions require special treatment in CTL.
  - A natural part of LTL.
- **Equivalences** and **preorders** between transition systems based on **simulation** and **bisimulation** relations rather than traces.



- 1 Introduction (Section 6.1)
- 2 Computation Tree Logic (Section 6.2)**
  - CTL - Syntax
  - CTL - Semantics
  - CTL Semantics - Equivalences
- 3 CTL Model Checking (Section 6.4)
- 4 Comparing CTL and LTL (Section 6.3)

# Computational Tree Logic - Syntax (6.2.1)

Modal logic over infinite **trees** [Clarke & Emerson 1981].

- Statements over states ( $\Phi$ ):

- $a \in AP$

atomic proposition

- $\neg\Phi$  and  $\Phi_1 \wedge \Phi_2$

negation and conjunction

- $\exists\varphi$

there *exists* a path fulfilling  $\varphi$

- $\forall\varphi$

*all* paths fulfill  $\varphi$

- Statements over paths ( $\varphi$ ):

- $\bigcirc\Phi$

the next state fulfills  $\Phi$

- $\Phi_1 \cup \Phi_2$

$\Phi_1$  holds until a  $\Phi_2$ -state is reached

# Computational Tree Logic - Syntax (6.2.1)

Modal logic over infinite **trees** [Clarke & Emerson 1981].

- **Statements over states ( $\Phi$ ):**

- $a \in AP$  atomic proposition
- $\neg \Phi$  and  $\Phi_1 \wedge \Phi_2$  negation and conjunction
- $\exists \varphi$  there *exists* a path fulfilling  $\varphi$
- $\forall \varphi$  *all* paths fulfill  $\varphi$

- **Statements over paths ( $\varphi$ ):**

- $\bigcirc \Phi$  the next state fulfills  $\Phi$
- $\Phi_1 \cup \Phi_2$   $\Phi_1$  holds until a  $\Phi_2$ -state is reached

⇒ Note that  $\bigcirc$  and  $\cup$  *alternate* with  $\forall$  and  $\exists$ :

- $\forall \bigcirc \bigcirc \Phi, \forall \exists \bigcirc \Phi \notin \text{CTL}$ , but  $\forall \bigcirc \forall \bigcirc \Phi$  and  $\forall \bigcirc \exists \bigcirc \Phi \in \text{CTL}$ .
- Four operators by the syntax rules:

$$\begin{array}{l} \forall \bigcirc \text{ (AX)}, \quad \forall \square \text{ (AG)}, \quad \forall U \text{ (AU)}, \quad \forall \diamond \text{ (AF)} \\ \exists \bigcirc \text{ (EX)}, \quad \exists \square \text{ (EG)}, \quad \exists U \text{ (EU)}, \quad \exists \diamond \text{ (EF)} \end{array}$$

- Check Example 6.2 in the book for some example formulas.

# Derived Operators

$$\text{potentially } \Phi: \quad \exists \diamond \Phi \quad = \quad \exists(\text{true} \cup \Phi)$$

$$\text{inevitably } \Phi: \quad \forall \diamond \Phi \quad = \quad \forall(\text{true} \cup \Phi)$$

$$\text{potentially always } \Phi: \quad \exists \square \Phi \quad = \quad \neg \forall \diamond \neg \Phi$$

$$\text{invariantly } \Phi: \quad \forall \square \Phi \quad = \quad \neg \exists \diamond \neg \Phi$$

$$\text{weak until:} \quad \exists(\Phi_1 \cup \Phi_2) \quad = \quad \neg \forall((\Phi_1 \wedge \neg \Phi_2) \cup (\neg \Phi_1 \wedge \neg \Phi_2))$$

$$\forall(\Phi_1 \cup \Phi_2) \quad = \quad \neg \exists((\Phi_1 \wedge \neg \Phi_2) \cup (\neg \Phi_1 \wedge \neg \Phi_2))$$

The boolean connectives are derived as usual.

# Example Properties in CTL

- Mutual exclusion:

$$\forall \square (\neg crit_1 \vee \neg crit_2)$$

- Starvation freedom:

$$(\forall \square \forall \diamond crit_1) \wedge (\forall \square \forall \diamond crit_2)$$

- Each red light is preceded by a yellow light:

$$\forall \square (yellow \vee \forall \bigcirc \neg red) ???$$

- Traffic light is infinitely often green:

$$\forall \square \forall \diamond green$$

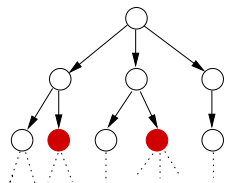
- Every request is eventually granted:

$$\forall \square (request \Rightarrow \forall \diamond response)$$

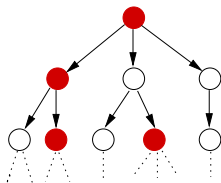
- In every reachable state, it is possible to return to the start state:

$$\forall \square \exists \diamond start$$

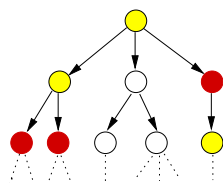
# CTL Semantics Visualization



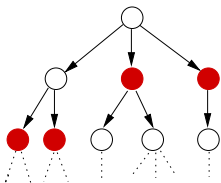
$\exists \diamond \text{red}$



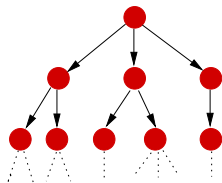
$\exists \square \text{red}$



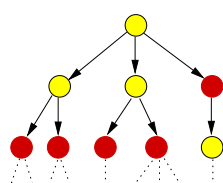
$\exists (\text{yellow} U \text{red})$



$\forall \diamond \text{red}$



$\forall \square \text{red}$



$\forall (\text{yellow} U \text{red})$

# CTL Semantics - State Formulas

Defined by a relation  $\models$  such that

$s \models \Phi$  if and only if formula  $\Phi$  holds in state  $s$

$s \models a$             iff  $a \in L(s)$

$s \models \neg \Phi$         iff  $\neg (s \models \Phi)$

$s \models \Phi \wedge \Psi$     iff  $(s \models \Phi) \wedge (s \models \Psi)$

$s \models \exists \varphi$         iff  $\pi \models \varphi$  for *some* path  $\pi$  that starts in  $s$

$s \models \forall \varphi$         iff  $\pi \models \varphi$  for *all* paths  $\pi$  that start in  $s$

# CTL Semantics - Path Formulas

Define a relation  $\models$  such that

$\pi \models \varphi$  if and only if path  $\pi$  satisfies  $\varphi$

$$\pi \models \bigcirc\Phi \quad \text{iff } \pi[1] \models \Phi$$

$$\pi \models \Phi \cup \Psi \quad \text{iff } (\exists j \geq 0. \pi[j] \models \Psi \wedge (\forall 0 \leq k < j. \pi[k] \models \Phi))$$

where  $\pi[i]$  denotes the state  $s_i$  in the path  $\pi$



# CTL Semantics - Transition System

Let  $TS = (S, Act, \rightarrow, I, AP, L)$  be a transition system.

- For CTL-state-formula  $\Phi$ , the *satisfaction set*  $Sat(\Phi)$  is defined by:

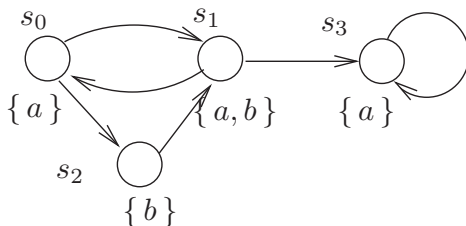
$$Sat(\Phi) = \{s \in S \mid s \models \Phi\}$$

- $TS$  satisfies CTL-formula  $\Phi$  iff  $\Phi$  holds in all its initial states:

$$TS \models \Phi \quad \text{if and only if} \quad \forall s_0 \in I. s_0 \models \Phi$$

This is equivalent to  $I \subseteq Sat(\Phi)$ .

# CTL Semantics - Examples



$\exists \bigcirc a$

$\forall \bigcirc a$

$\exists \square a$

$\forall \square a$

$\forall (a \cup b)$

## Remark 6.10 The Semantics of Negation

$TS \not\models \Phi$  and  $TS \not\models \neg\Phi$  is possible due to having multiple initial states, e.g.,  $s_0 \models \exists\Box\Phi$  and  $s'_0 \not\models \exists\Box\Phi$ .



$TS \not\models \exists\Box a$  and  $TS \not\models \neg\exists\Box a$

## 6.2.3 CTL Equivalence

### Definition 6.12

CTL-formulas  $\Phi$  and  $\Psi$  (over  $AP$ ) are *equivalent*, denoted  $\Phi \equiv \Psi$  if and only if  $Sat(\Phi) = Sat(\Psi)$  for *all* transition systems  $TS$  over  $AP$ .

$$\Phi \equiv \Psi \quad \text{iff} \quad (TS \models \Phi \quad \text{if and only if} \quad TS \models \Psi)$$

# Duality Laws

$$\forall \bigcirc \Phi \equiv \neg \exists \bigcirc \neg \Phi$$

$$\exists \bigcirc \Phi \equiv \neg \forall \bigcirc \neg \Phi$$

$$\forall \diamond \Phi \equiv \neg \exists \square \neg \Phi$$

$$\exists \diamond \Phi \equiv \neg \forall \square \neg \Phi$$

$$\forall (\Phi \cup \Psi) \equiv \neg \exists ((\Phi \wedge \neg \Psi) \cup (\neg \Phi \wedge \neg \Psi))$$

# Expansion Laws

Recall in LTL:  $\varphi \text{ U } \psi \equiv \psi \vee (\varphi \wedge \text{O}(\varphi \text{ U } \psi))$

In CTL:

$$\forall(\Phi \text{ U } \Psi) \equiv \Psi \vee (\Phi \wedge \forall \text{O} \forall(\Phi \text{ U } \Psi))$$

$$\forall \diamond \Phi \equiv \Phi \vee \forall \text{O} \forall \diamond \Phi$$

$$\forall \square \Phi \equiv \Phi \wedge \forall \text{O} \forall \square \Phi$$

$$\exists(\Phi \text{ U } \Psi) \equiv \Psi \vee (\Phi \wedge \exists \text{O} \exists(\Phi \text{ U } \Psi))$$

$$\exists \diamond \Phi \equiv \Phi \vee \exists \text{O} \exists \diamond \Phi$$

$$\exists \square \Phi \equiv \Phi \wedge \exists \text{O} \exists \square \Phi$$

# Distributive Laws (1)

Recall in LTL:  $\Box(\varphi \wedge \psi) \equiv \Box\varphi \wedge \Box\psi$  and  $\Diamond(\varphi \vee \psi) \equiv \Diamond\varphi \vee \Diamond\psi$

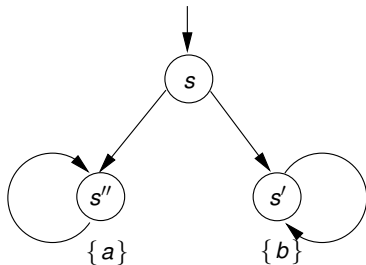
In CTL:

$$\forall\Box(\Phi \wedge \Psi) \equiv \forall\Box\Phi \wedge \forall\Box\Psi$$

$$\exists\Diamond(\Phi \vee \Psi) \equiv \exists\Diamond\Phi \vee \exists\Diamond\Psi$$

## Distributive Laws (2)

Note that  $\exists \Box(\Phi \wedge \Psi) \not\equiv \exists \Box\Phi \wedge \exists \Box\Psi$  and  
 $\forall \Diamond(\Phi \vee \Psi) \not\equiv \forall \Diamond\Phi \vee \forall \Diamond\Psi$ .



$s \models \forall \Diamond(a \vee b)$  since

$s' \models a \implies s' \models a \vee b$

$s'' \models a \implies s'' \models a \vee b$

However,  $s \not\models \forall \Diamond a$  and  $s \not\models \forall \Diamond b$ .



- 1 Introduction (Section 6.1)
- 2 Computation Tree Logic (Section 6.2)
  - CTL - Syntax
  - CTL - Semantics
  - CTL Semantics - Equivalences
- 3 CTL Model Checking (Section 6.4)**
- 4 Comparing CTL and LTL (Section 6.3)

## Existential Normal Form (ENF) – Section 6.2.4

The set of CTL formulas in *existential normal form* (ENF) is given by:

$$\Phi ::= \text{true} \mid a \mid \Phi_1 \wedge \Phi_2 \mid \neg\Phi \mid \text{EX } \Phi \mid \exists(\Phi_1 \text{ U } \Phi_2) \mid \text{EG } \Phi$$

- For each CTL formula, there exists an equivalent CTL formula in ENF.

$$\text{AX } \Phi \quad \equiv \quad \neg\text{EX } \neg\Phi$$

$$\forall(\Phi \text{ U } \Psi) \quad \equiv \quad \neg\exists(\neg\Psi \text{ U } (\neg\Phi \wedge \neg\Psi)) \wedge \neg\text{EG } \neg\Psi$$

- Handle only  $\text{EX } \Phi$ ,  $\text{EG } \Phi$ , and  $\exists(\Phi_1 \text{ U } \Phi_2)$ .

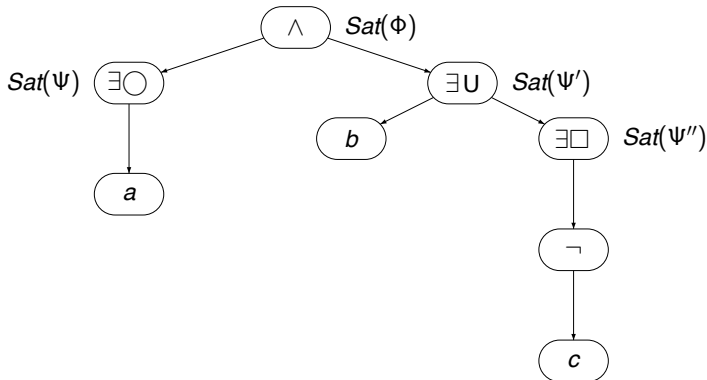
# CTL Model Checking

- How to check whether  $TS$  satisfies CTL formula  $\widehat{\Phi}$ ?
  - Convert the formula  $\widehat{\Phi}$  into the equivalent  $\Phi$  in ENF.
  - Compute *recursively* the set  $Sat(\Phi) = \{s \in S \mid s \models \Phi\}$ .
  - $TS \models \Phi$  if and only if  $I \subseteq Sat(\Phi)$ .
- Recursive **bottom-up** computation of  $Sat(\Phi)$ :
  - Consider the **parse-tree** of  $\Phi$ .
  - Start to compute  $Sat(\Psi_i)$ , for all leafs, then go one level up in the tree and determine  $Sat(\cdot)$  for these nodes, repeat until the **root** is computed.

$$\text{e.g., } Sat(\underbrace{\Psi_1 \wedge \Psi_2}_{\text{node at level } i}) = Sat(\underbrace{\Psi_1}_{\text{node at level } i+1}) \cap Sat(\underbrace{\Psi_2}_{\text{node at level } i+1})$$

# CTL Model Checking: An Example

$$\Phi = \underbrace{EX a}_{\Psi} \wedge \underbrace{\exists(b U EG \neg c)}_{\Psi'}$$



## Theorem 6.23 Characterization of $Sat$ (1)

For all CTL formulas  $\Phi, \Psi$  over  $AP$  it holds:

$$Sat(\text{true}) = S$$

$$Sat(a) = \{s \in S \mid a \in L(s)\}, \text{ for any } a \in AP$$

$$Sat(\Phi \wedge \Psi) = Sat(\Phi) \cap Sat(\Psi)$$

$$Sat(\neg\Phi) = S \setminus Sat(\Phi)$$

$$Sat(EX \Phi) = \{s \in S \mid Post(s) \cap Sat(\Phi) \neq \emptyset\}$$

where  $TS = (S, Act, \rightarrow, I, AP, L)$  is a transition system without terminal states.

## Theorem 6.23 Characterization of $Sat$ (2)

- $Sat(\exists(\Phi \cup \Psi))$  is the smallest subset  $T$  of  $S$ , such that:
  - ①  $Sat(\Psi) \subseteq T$  and
  - ②  $(s \in Sat(\Phi) \text{ and } Post(s) \cap T \neq \emptyset)$  implies  $s \in T$
- $Sat(EG \Phi)$  is the largest subset  $T$  of  $S$ , such that:
  - ①  $T \subseteq Sat(\Phi)$  and
  - ②  $s \in T$  implies  $Post(s) \cap T \neq \emptyset$

where  $TS = (S, Act, \rightarrow, I, AP, L)$  is a transition system without terminal states.

# Algorithm 14 Computation of $Sat$

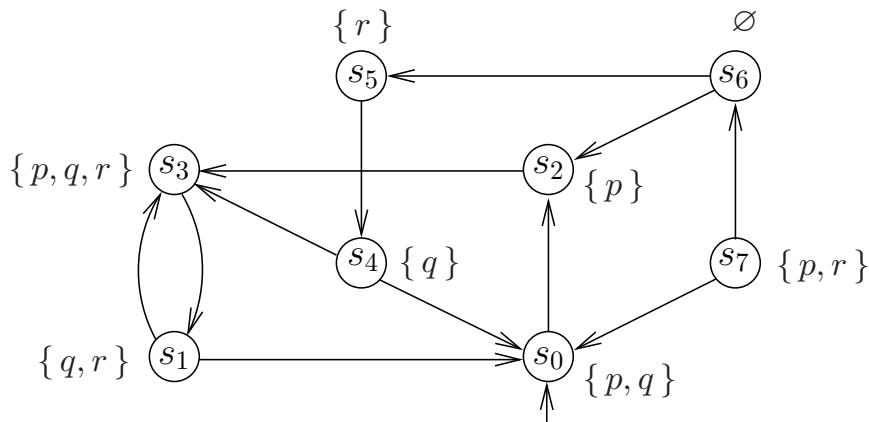
**switch**( $\Phi$ ):

```
 $a$            : return  $\{s \in S \mid a \in L(s)\}$ ;  
...         : .....  
EX  $\Psi$       : return  $\{s \in S \mid Post(s) \cap Sat(\Psi) \neq \emptyset\}$ ;  
 $\exists(\Phi_1 \cup \Phi_2)$  :  $T := Sat(\Phi_2)$ ;   compute the smallest fixed point  
               while  $\{s \in Sat(\Phi_1) \setminus T \mid Post(s) \cap T \neq \emptyset\} \neq \emptyset$  do  
                   let  $s \in \{s \in Sat(\Phi_1) \setminus T \mid Post(s) \cap T \neq \emptyset\}$ ;  
                        $T := T \cup \{s\}$ ;  
               od;  
               return  $T$ ;  
  
EG  $\Phi$       :  $T := Sat(\Phi)$ ;   compute the greatest fixed point  
               while  $\{s \in T \mid Post(s) \cap T = \emptyset\} \neq \emptyset$  do  
                   let  $s \in \{s \in T \mid Post(s) \cap T = \emptyset\}$ ;  
                        $T := T \setminus \{s\}$ ;  
               od;  
               return  $T$ ;
```

**end switch**

# Computing $Sat(\exists(\Phi \cup \Psi))$ – An Example

Check  $EF((p = r) \wedge (p \neq q)) \equiv \exists(true \cup ((p = r) \wedge (p \neq q)))$





# Computing $Sat(\exists(\Phi \cup \Psi))$ – Summary

- $Sat(\exists(\Phi \cup \Psi))$  is the smallest set  $T \subseteq S$  such that

$$(1) \ Sat(\Psi) \subseteq T \quad \text{and} \quad (2) \ \{s \in T \mid s \models \Phi \wedge Post(s) \cap T \neq \emptyset\}$$

- Initially,  $T_0 = \{Sat(\Psi)\}$ .
- Iteratively compute

$$T_{i+1} = T_i \cup \{s \in Sat(\Phi) \mid Post(s) \cap T_i \neq \emptyset\} \text{ for } i \geq 0.$$

- In other words, computing  $Sat(\exists(\Phi \cup \Psi))$  results in

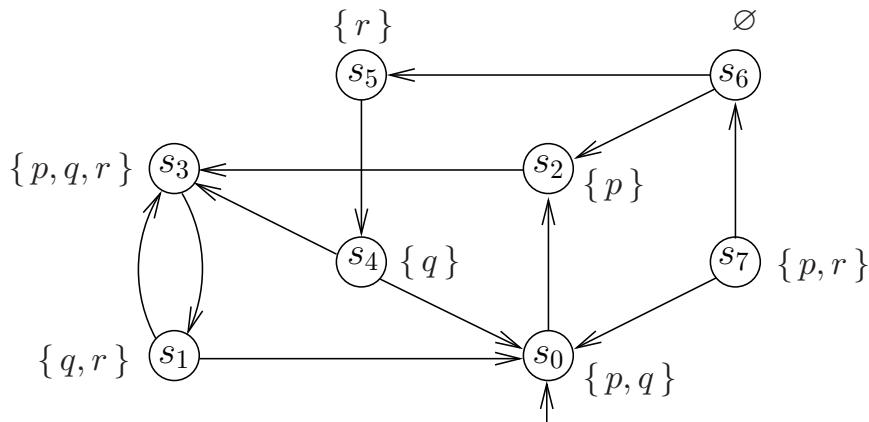
$$T_0 \subseteq T_1 \subseteq \dots \subseteq T_j \subseteq T_{j+1} \subseteq \dots$$

- Since we assume  $TS$  to be finite, there exists a  $j \geq 0$  such that

$$T_j = T_{j+1} = \dots = Sat(\exists(\Phi \cup \Psi))$$

# Computing $Sat(EG \Phi)$ – An Example

Check  $EG q$



# Computing $Sat(EG \Phi)$ – Summary

- $Sat(EG \Phi)$  is the largest set  $T \subseteq S$  such that

$$(1) T \subseteq Sat(\Phi) \quad \text{and} \quad (2) \{s \in T \mid Post(s) \cap T \neq \emptyset\}$$

- Initially,  $T_0 = Sat(\Phi)$ .
- Then, iteratively compute

$$T_{i+1} = T_i \cap \{s \in Sat(\Phi) \mid Post(s) \cap T_i \neq \emptyset\}$$

- Thus, computing  $Sat(EG \Phi)$  results in

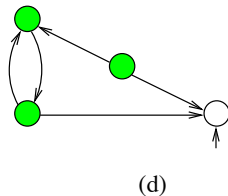
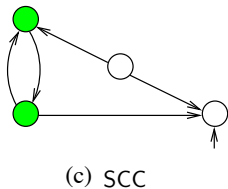
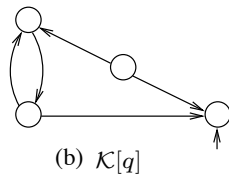
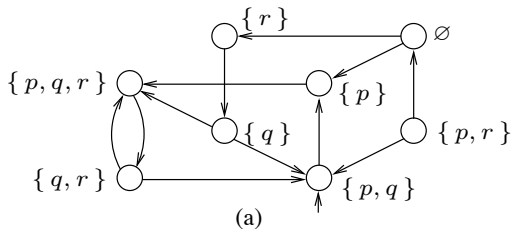
$$T_0 \supseteq T_1 \supseteq \dots$$

- Since we assume  $TS$  to be finite, there exists a  $j \geq 0$  such that

$$T_j = T_{j+1} = \dots = Sat(EG \Phi)$$

# Alternative Algorithm for Computing $Sat(EG \Phi)$

Check  $EG q$

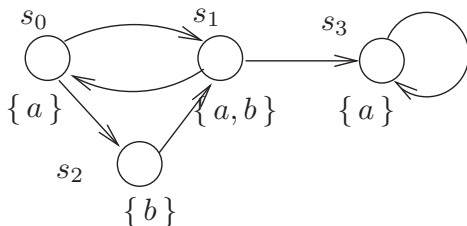


## 6.4.3 Time Complexity

For transition system  $TS$  with  $N$  states and  $M$  transitions, and CTL formula  $\Phi$ , the CTL model-checking problem  $TS \models \Phi$  can be determined in time  $\mathcal{O}(|\Phi| \cdot (N + M))$ .

This result applies to both algorithms for EG  $\Phi$ .

# CTL Semantics - Practice



$$\exists \diamond (\exists \square a)$$
$$\exists (a \text{ U } (\neg a \wedge \forall (\neg a \text{ U } b)))$$

- 1 Introduction (Section 6.1)
- 2 Computation Tree Logic (Section 6.2)
  - CTL - Syntax
  - CTL - Semantics
  - CTL Semantics - Equivalences
- 3 CTL Model Checking (Section 6.4)
- 4 **Comparing CTL and LTL (Section 6.3)**

## 6.3 Equivalence of LTL and CTL Formulas

### Definition 6.17

CTL-formula  $\Phi$  and LTL-formula  $\varphi$  (both over  $AP$ ) are *equivalent*, denoted  $\Phi \equiv \varphi$ , if for *any* transition system  $TS$  (over  $AP$ ):

$$TS \models \Phi \quad \text{if and only if} \quad TS \models \varphi$$

### Theorem 6.18

Let  $\Phi$  be a CTL-formula, and  $\varphi$  the LTL-formula obtained by eliminating all path quantifiers in  $\Phi$ . Then: [Clarke & Draghicescu]

$$\Phi \equiv \varphi$$

or

there does not exist any LTL-formula that is equivalent to  $\Phi$ .



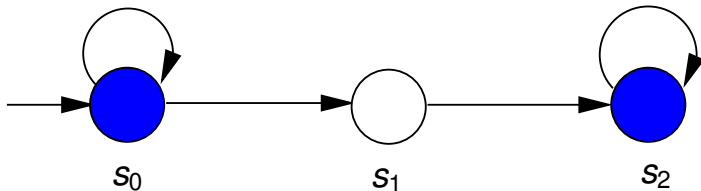
# LTL and CTL are Incomparable

- Some LTL-formulas cannot be expressed in CTL, e.g.,
  - $\diamond \square a$
  - $\diamond(a \wedge \bigcirc a)$
- Some CTL-formulas cannot be expressed in LTL, e.g.,
  - $\forall \diamond \forall \square a$
  - $\forall \diamond(a \wedge \forall \bigcirc a)$
  - $\forall \square \exists \diamond a$

$\Rightarrow$  Cannot be expressed = there does not exist an **equivalent** formula.

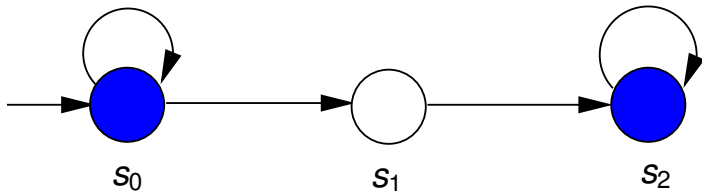
# Comparing LTL and CTL (Lemma 6.19)

$$\forall \diamond \forall \square a \neq \diamond \square a.$$



# Comparing LTL and CTL (Lemma 6.19)

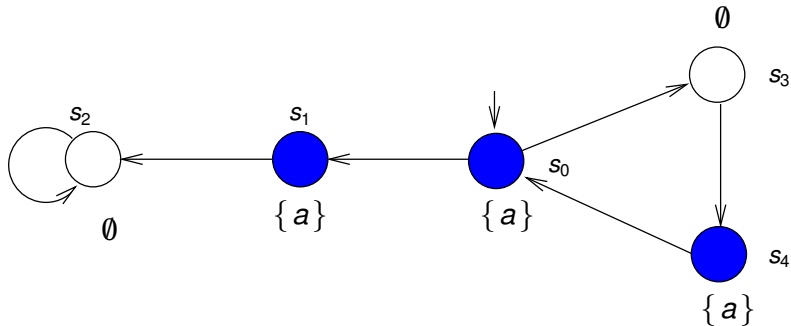
$$\forall \diamond \forall \square a \neq \diamond \square a.$$



$$s_0 \models \diamond \square a \quad \text{but} \quad \underbrace{s_0 \not\models \forall \diamond \forall \square a}_{\text{path } s_0^\omega \text{ violates it}}$$

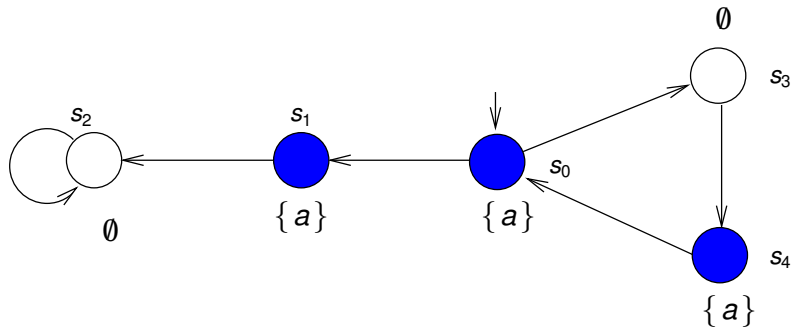
# Comparing LTL and CTL (Lemma 6.20)

$$\forall \diamond(a \wedge \forall \bigcirc a) \not\equiv \diamond(a \wedge \bigcirc a).$$



# Comparing LTL and CTL (Lemma 6.20)

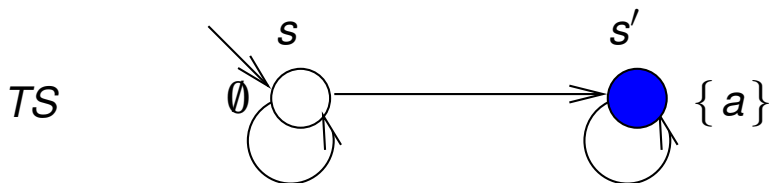
$$\forall \diamond(a \wedge \forall \bigcirc a) \not\equiv \diamond(a \wedge \bigcirc a).$$



$s_0 \models \diamond(a \wedge \bigcirc a)$  **but**  $s_0 \not\models \forall \diamond(a \wedge \forall \bigcirc a)$   
 path  $s_0 s_1 (s_2)^\omega$  violates it

## Comparing LTL and CTL (3)

The CTL-formula  $\forall \square \exists \diamond a$  cannot be expressed in LTL



# Linear-Time vs. Branching-Time Summary

Aspect	Linear Time	Branching Time
"behavior" in a state $s$	path-based: $trace(s)$	state-based: computation tree of $s$
temporal logic	LTL: path formulas $\varphi$ $s \models \varphi$ iff $\forall \pi \in \rho(s). \pi \models \varphi$	CTL: state formulas existential path quantification $\exists \varphi$ universal path quantification: $\forall \varphi$
complexity of the model checking problems	PSPACE-complete $\mathcal{O}( TS  \cdot 2^{ \varphi })$	PTIME $\mathcal{O}( TS  \cdot  \Phi )$
implementation-relation	trace inclusion and the like (proof is PSPACE-complete)	simulation and bisimulation (proof in polynomial time)
fairness	no special techniques	special techniques needed

# Conclusion

- Branching time semantics of computation
- CTL for expressing branching time properties
- CTL model checking algorithms
- CTL and LTL are NOT comparable